# Translog Factor Demand Systems: The KLEM Model

by

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### The KLEM Model

- Translog Factor Demand System
  - U.S. Manufacturing, 1957-1971
  - Price and quantity data on capital (K), labor (L), energy (E), materials (M), and ten instrumental variables.

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Files klem.doc and klem.dat in pub/arg/data at ftp.econ.duke.edu.

### • Features

- A linear multivariate regression if prices exogenous and errors additive.
- A nonlinear multivariate regression if prices exogenous and errors logistic normal.
- A linear simultaneous equations system if prices endogenous and errors additive.
- A nonlinear simultaneous equations system if prices endogenous and errors logistic normal.

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## <u>References</u>

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## Factor Demand Theory in Levels

The producer's cost function c(p, u) gives the minimum cost of producing output u during a given period using inputs  $q = (q_1, \ldots, q_N)'$  at prices  $p = (p_1, \ldots, p_N)'$ .

Linear homogeneity:  $\lambda c(p, u) = c(\lambda p, u)$ 

Constant returns: c(p, u) = uc(p)

Shepard's lemma:  $q = \frac{\partial}{\partial p} c(p, u)$ 

 $\text{Elasticities of substitution: } \sigma_{ij} = \frac{c(p,u) \frac{\partial^2}{\partial p_i \partial p_j} c(p,u)}{\frac{\partial}{\partial p_i} c(p,u) \frac{\partial}{\partial p_j} c(p,u)}$ 

Price elasticities:  $\eta_{ij} = \frac{\partial \log q_i}{\partial \log p_i} = p_j \sigma_{ij} \frac{\frac{\partial}{\partial p_j} c(p,u)}{c(p,u)}$ 

### Factor Demand Theory in Logarithms

The producer's log cost function g(l, v) gives the minimum cost of producing log output v =log u during a given period using factor cost shares  $s = (p_1q_1, \ldots, p_Nq_N)'/(\sum_{i=1}^N p_iq_i)$  at log prices  $\ell = (\log p_1, \ldots, \log p_N)'$ .

Linear homogeneity:  $g(\ell + \tau 1, v) = \tau + g(\ell, v)$ where I = (1, ..., 1)'

Constant returns:  $g(\ell, v) = v + g(\ell)$ 

Shepard's lemma:  $s = \frac{\partial}{\partial \ell} g(\ell, v)$ 

Elasticities of subst.:  $\Sigma = G^{-1} \Big[ \frac{\partial^2 g}{\partial \ell \partial \ell} + \frac{\partial g}{\partial \ell} \frac{\partial g}{\partial \ell} - G \Big] G^{-1}$ where  $G = \text{diag}(\frac{\partial g}{\partial \ell})$ 

Price elasticities:  $\eta = \Sigma G$ 

Constant Returns KLEM Translog Model (1)

Factor cost shares: 
$$s = \begin{pmatrix} M_K \\ M_L \\ M_E \\ M_M \end{pmatrix}$$
  
Log factor prices:  $\ell = \begin{pmatrix} \log P_K \\ \log P_L \\ \log P_E \\ \log P_M \end{pmatrix}$ 

Translog log cost function:

$$g(\ell, v) = \alpha \ell + \frac{1}{2} \ell' B \ell + v$$

where

$$\alpha = \begin{pmatrix} \alpha_K \\ \alpha_L \\ \alpha_E \\ \alpha_M \end{pmatrix} \quad B = \begin{pmatrix} \gamma_{KK} & \gamma_{KL} & \gamma_{KE} & \gamma_{KM} \\ \gamma_{LK} & \gamma_{LL} & \gamma_{LE} & \gamma_{LM} \\ \gamma_{EK} & \gamma_{EL} & \gamma_{EE} & \gamma_{EM} \\ \gamma_{MK} & \gamma_{ML} & \gamma_{ME} & \gamma_{MM} \end{pmatrix}$$

Constant Returns KLEM Translog Model (1)

Because

$$\frac{\partial}{\partial \ell} \ell' B \ell = (B + B')\ell$$
$$\frac{\partial^2}{\partial \ell \partial \ell'} \ell' B \ell = (B + B')$$

and (B + B') is symmetric, we might just as well assume that B is symmetric to start with, which we will.

The Translog factor demand system is

 $s = \alpha + B\ell$ 

whose coefficients are subject to the following restrictions:

Linear homogeneity :  $\alpha' 1 = 1$ , B1 = 0Symmetry : B = B'Adding up:  $\alpha' 1 = 1$ , 1'B = 0

some of which are redundant.

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### KLEM Translog Model, Additive Errors (1)

All one can get out of a deterministic model such as above a specification for some measure of central tendency of some distribution. The simplest assumption is additive measurement error:

$$s_t = \alpha + B\ell_t + e_t$$

where

$$\mathcal{E}e_t = 0$$
$$\mathcal{E}e_s e'_t = \begin{cases} \Omega & s = t \\ 0 & s \neq t \end{cases}$$
$$t = 1, \dots, n$$

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#### KLEM Translog Model, Additive Errors (2)

This specification should remain invariant to linear transformation. That is, we could just as well choose to analyze the model

 $Ps_t = P\alpha + PB\ell_t + Pe_t$ 

for some matrix  $P_{\rm i}$  indeed, this is how one usually does generalized least squares in practice. Consider

$$P = \left(\begin{array}{rrrr} 1 & 0 & 0 & 0\\ 0 & 1 & 0 & 0\\ 0 & 0 & 1 & 0\\ 1 & 1 & 1 & 1 \end{array}\right)$$

We get

 $s_{Kt} = \alpha_K + \gamma_{KK}\ell_{Kt} + \gamma_{KL}\ell_{Lt} + \gamma_{KE}\ell_{Et} + \gamma_{KM}\ell_{Mt} + e_{Kt}$ 

 $s_{Lt} = \alpha_L + \gamma_{LK}\ell_{Kt} + \gamma_{LL}\ell_{Lt} + \gamma_{LE}\ell_{Et} + \gamma_{LM}\ell_{Mt} + e_{Lt}$ 

 $s_{Et} = \alpha_E + \gamma_{EK}\ell_{Kt} + \gamma_{EL}\ell_{Lt} + \gamma_{EE}\ell_{Et} + \gamma_{EM}\ell_{Mt} + e_{Et}$ 

$$1 = \sum_{i=K}^{M} s_i = \sum_{i=K}^{M} \alpha_i + \sum_{j=K}^{M} \left( \sum_{i=K}^{M} \gamma_{ij} \right) \ell_{jt} + \sum_{i=K}^{M} e_i$$

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### KLEM Translog Model, Additive Errors (3)

Consider the implications of

$$1 = \sum_{i=K}^{M} \alpha_i + \sum_{j=K}^{M} \left( \sum_{i=K}^{M} \gamma_{ij} \right) \ell_{jt} + \sum_{i=K}^{M} e_{it}$$

Because the LHS is non-random, we have

$$\operatorname{Var}\left(\sum_{i=K}^{M} e_{it}\right) = 0$$

The mean and variance of  $\sum_{i=K}^M e_{it}$  are therefore both zero, which implies  $\sum_{i=K}^M e_{it}$  is identically zero for all t. We have now that

$$1 = \sum_{i=K}^{M} \alpha_i + \sum_{j=K}^{M} \left( \sum_{i=K}^{M} \gamma_{ij} \right) \ell_{jt}$$

Because this must hold for all t, we conclude that

$$\sum_{i=K}^{M} \alpha_i = 1 \text{ and } \sum_{i=K}^{M} \gamma_{ij} = 0 \text{ for } j = K, L, E, M,$$

which is the adding up restriction.

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### KLEM Translog Model, Additive Errors (4)

The KLEM translog factor demand model with additive errors is therefore a three equation linear system

$$\begin{split} s_{Kt} &= \alpha_{K} + \gamma_{KK}\ell_{kt} + \gamma_{KL}\ell_{Lt} + \gamma_{KE}\ell_{Et} + \gamma_{KM}\ell_{Mt} + e_{Kt} \\ s_{Lt} &= \alpha_{L} + \gamma_{LK}\ell_{Kt} + \gamma_{LL}\ell_{Lt} + \gamma_{LE}\ell_{Et} + \gamma_{LM}\ell_{Mt} + e_{Lt} \\ s_{Et} &= \alpha_{E} + \gamma_{EK}\ell_{Kt} + \gamma_{EL}\ell_{Lt} + \gamma_{EE}\ell_{Et} + \gamma_{EM}\ell_{Mt} + e_{Et} \end{split}$$

subject to the parametric constraint of adding up

$$\sum_{i=K}^{M} \alpha_i = 1 \text{ and } \sum_{i=K}^{M} \gamma_{ij} = 0 \text{ for } j = K, L, E, M,$$

The parametric constraint is not binding on the parameters of the three equations, which means that one gets  $\hat{\alpha}_M$  from estimates of the parameters of the system using the constraint

 $\hat{\alpha}_M = \mathbf{1} - \hat{\alpha}_K - \hat{\alpha}_L - \hat{\alpha}_E.$ 

$$\hat{\gamma}_{Mj} = -(\hat{\gamma}_{Kj} + \hat{\gamma}_{Lj} + \hat{\gamma}_{Ej})$$

for j = K, L, E, M.

Similarly

The errors  $u_t = (e_{Kt}, e_{Lt}, e_{Et})'$  satisfy

$$\mathcal{E} u_t = 0$$

$$\mathcal{E}u_s u_t' = \begin{cases} \Sigma & s = t \\ 0 & s \neq t \end{cases}$$
$$t = 1, \dots, n$$

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## KLEM Model, Logistic Normal Errors (1)

The assumption of additive errors is implausible for a variety of reasons. One of them is that the errors must be heterogeneous due to the restriction that  $0 < \mathcal{E}s_{it} + e_{it} < 1$  which implies that

$$-\mathcal{E}s_{it} < e_{it} < 1 - \mathcal{E}s_{it}$$

Thus, the support of the density must depend on  $\ell_t$  which makes an assumption that second moments do not implausible. While one could use the methods of Chapter 2 to correct for heteroskedasticity, starting with plausible assumptions seems preferable.

Rossi(1983) in an extensive empirical investigation determined that the logistic normal assumption is more plausible. That assumption implies

$$\begin{pmatrix} \log(s_K/s_M) - \log[(\mathcal{E}s_K)/(\mathcal{E}s_M)] \\ \log(s_L/s_M) - \log[(\mathcal{E}s_L)/(\mathcal{E}s_M)] \\ \log(s_E/s_M) - \log[(\mathcal{E}s_E)/(\mathcal{E}s_M)] \end{pmatrix} \sim N_3(0, \Sigma)$$

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KLEM Model, Logistic Normal Errors (2)

If we put

$$y_t = \begin{pmatrix} \log(s_{Kt}/s_{Mt}) \\ \log(s_{Lt}/s_{Mt}) \\ \log(s_{Et}/s_{Mt}) \end{pmatrix}$$

the model becomes

$$y_t = f[\ell_t, (\alpha, B)] + e_t$$

where

$$f[\ell,(\alpha,B)] = \begin{pmatrix} \log \frac{\alpha_K + \gamma_{KK}\ell_K + \gamma_{KL}\ell_L + \gamma_{KM}\ell_M + \gamma_{KE}\ell_E}{\alpha_M + \gamma_M \kappa^\ell_K + \gamma_M \ell_L + \gamma_M m^\ell_M + \gamma_M E^\ell_E} \\ \log \frac{\alpha_L + \gamma_{LK}\ell_K + \gamma_{LL}\ell_L + \gamma_L m^\ell_M + \gamma_L e^\ell_E}{\alpha_M + \gamma_M \kappa^\ell_K + \gamma_M \ell_L + \gamma_M m^\ell_M + \gamma_M E^\ell_E} \\ \log \frac{\alpha_E + \gamma_E \kappa^\ell_K + \gamma_E \ell_L + \gamma_E m^\ell_M + \gamma_E e^\ell_E}{\alpha_M + \gamma_M \kappa^\ell_K + \gamma_M L^\ell_L + \gamma_M m^\ell_M + \gamma_M E^\ell_E} \end{pmatrix}$$

subject to  $1'\alpha = 1$  and 1'B = 0. This is a three equation nonlinear system.

The nonhomogeneous restriction  $1'\alpha = 1$  must be imposed to get identification. Assuming that  $\alpha_M \neq 0$ , one can impose the normalization rule  $\alpha_M = 1$  instead.

### KLEM Model, Logistic Normal Errors (3)

One can impose the hypothesis of symmetry and the normalization rule as follows:

 $\alpha_K = \theta_1$  $\alpha_E = \theta_{10}$  $\gamma_{KK} = \theta_2$  $\gamma_{EK} = \theta_4$  $\begin{array}{l} \gamma_{KL} = \theta_3 \\ \gamma_{KE} = \theta_4 \end{array}$  $\gamma_{KL} = \theta_3$  $\gamma_{KE} = \theta_4$  $\gamma_{KM} =$  $\gamma_{KM} = \theta_5$  $\theta_5$  $\alpha_L = \theta_6$  $\alpha_M = 1$  $\gamma_{MK} = \theta_5$  $\gamma_{LK} = \theta_3$  $\gamma_{ML} = \theta_9$  $\gamma_{LL} = \theta_7$  $\gamma_{LE} = \theta_8$  $\gamma_{ME} = \theta_{12}$  $\gamma_{MM}$  =  $\theta_{13}$  $\gamma_{LM} = \theta_9$ 

the response function becomes

$$f(x,\theta) = \begin{pmatrix} \log \frac{\theta_1 + \theta_2 x_1 + \theta_3 x_2 + \theta_4 x_3 + \theta_5 x_4}{1 + \theta_5 x_1 + \theta_9 x_2 + \theta_1 2 x_3 + \theta_1 3 x_4} \\ \log \frac{\theta_6 + \theta_3 x_1 + \theta_7 x_2 + \theta_3 x_3 + \theta_9 x_4}{1 + \theta_5 x_1 + \theta_9 x_2 + \theta_1 2 x_3 + \theta_1 3 x_4} \\ \log \frac{\theta_{10} + \theta_4 x_1 + \theta_8 x_2 + \theta_{11} x_3 + \theta_{12} x_4}{1 + \theta_5 x_1 + \theta_9 x_2 + \theta_{12} x_3 + \theta_{13} x_4} \end{pmatrix}$$
where  $x = \ell$ .

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